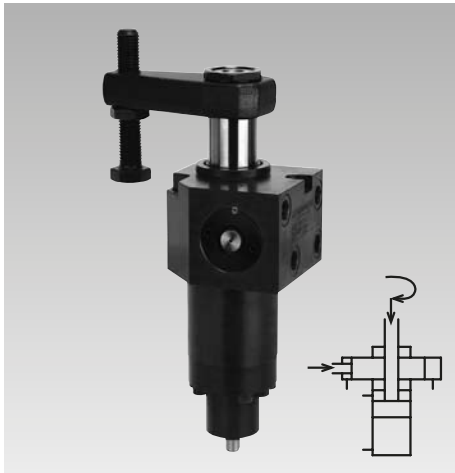




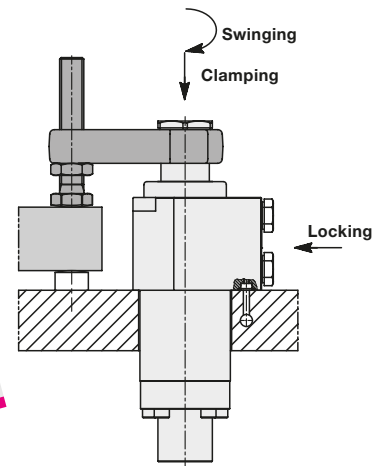
Swing Clamp with Piston Rod Locking

Top flange, reinforced swing mechanism, position monitoring optional, double acting, max. operating pressure 250 bar



Advantages

- High process safety
- Self-locking patented piston rod locking
- Reinforced swing mechanism
- Optional position monitoring electrical or pneumatic
- Compact design
- Alternatively pipe thread or drilled channels
- Standard FKM wiper
- Metallic wiper optional



Application

Hydraulic swing clamps are used for clamping of workpieces, when it is essential to keep the clamping area free of straps and clamping components for unrestricted workpiece loading and unloading.

The version with piston rod locking maintains the clamping force also after a pressure drop.

This series is particularly suited for

- Pallet changing systems
- Transfer lines
- Workpiece change with handling systems
- Automatic manufacturing systems
- Assembly lines
- Test systems for motors, gears, axis ...

Function

The hydraulic swing clamp is a pull-type cylinder where a part of the total stroke is used to swing the piston. The piston rod locking is made by a separately-controlled double-acting wedge-shaped piston.

Clamping: 1. Swinging and clamping
2. Locking

Unclamping: 1. Release locking
2. Unclamping and swinging back

Self-locking

The wedge-shaped piston is designed as a self-locking piston so that the swing clamp can be depressurised after clamping. The previously generated clamping force will be maintained.

Conditions: Before depressurising, the locking pressure must be available at least for 3 seconds.

Control and important notes

See page 4.

Special features

Self-locking piston rod locking

The patented piston rod locking is made by friction locking by a separately-controllable double-acting wedge-shaped piston with self-locking. In the case of a pressure drop or complete pressure reduction, the clamping force will be maintained.

Reinforced swing mechanism

The reinforced swing mechanism without overload protection device endures a collision with the workpiece during clamping up to a pressure of 100 bar.

Accessory - Position monitoring

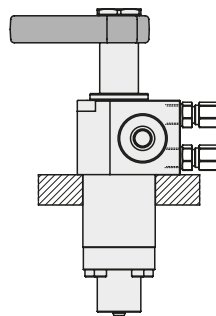
As an option, the swing clamps are available with an extended switch rod at the cylinder bottom. Here a control cam can be fixed to control the clamping and unclamping position. As accessories pneumatic and electrical position monitorings are available.

Option: metallic wiper

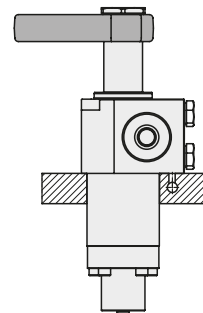
The optionally available metallic wiper protects the FKM wiper against mechanical damage.

Connecting possibilities

Pipe thread

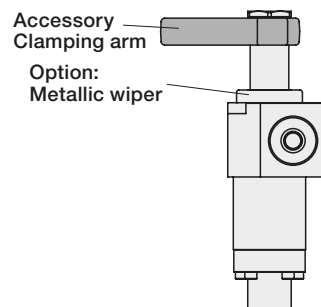


Drilled channels

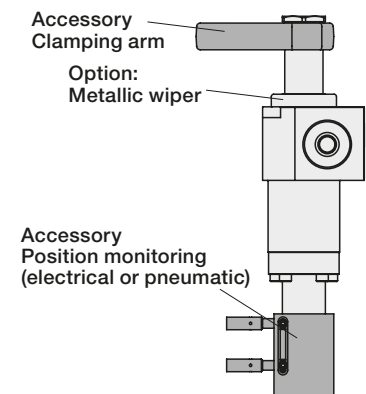


Versions

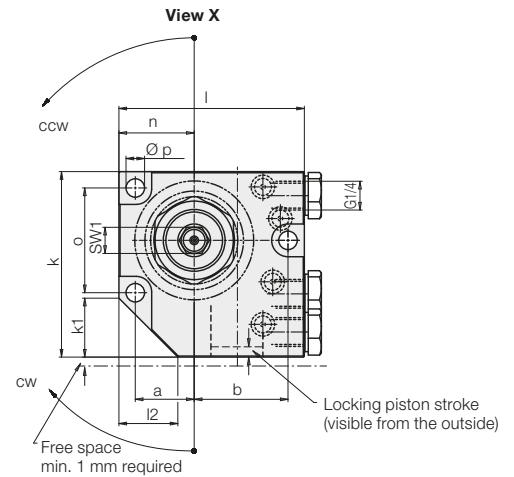
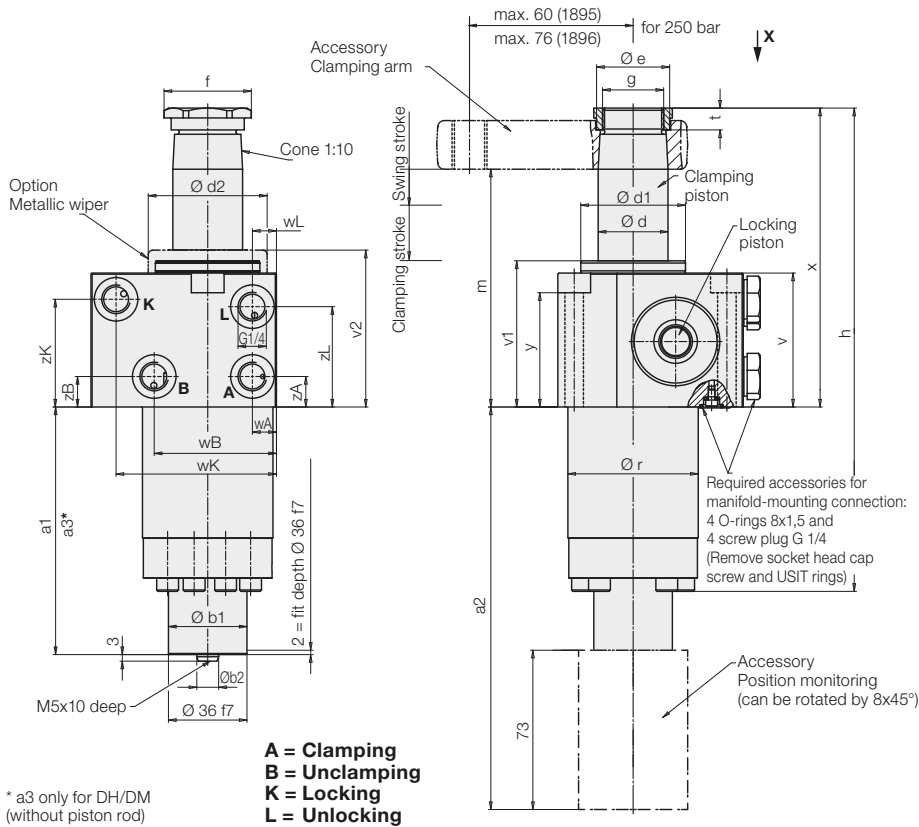
KDH, KDM: without switch rod



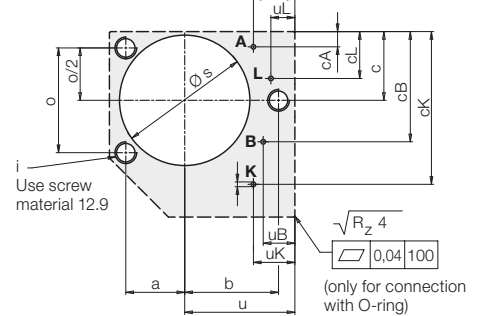
KMH, KMM: with switch rod



Dimensions Position monitoring

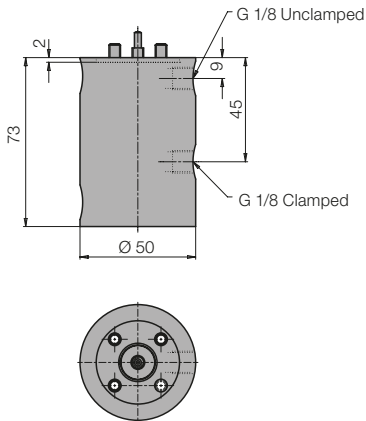


Connecting scheme

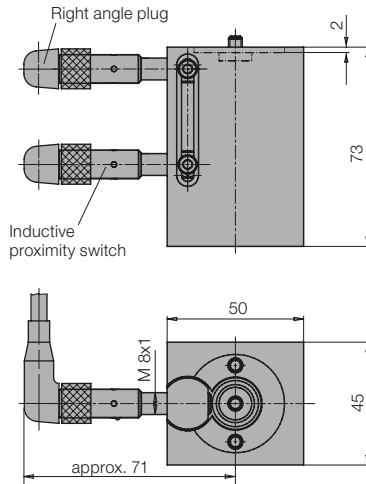


Ports A, B, K, L: max. Ø 6 mm

Accessory - Position monitoring Pneumatic position monitoring



Electrical position monitoring

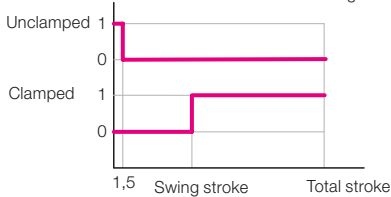


Technical data for proximity switches

| | |
|----------------------------------|-----------------|
| Operating voltage | 10...30 V DC |
| Residual ripple max. | 15 % |
| Constant current max. | 200 mA |
| Switching function | interlock |
| Output | PNP |
| Body material | stainless steel |
| Code class | IP 67 |
| Environmental temperature | -25...+70°C |
| Connection type | Plug |
| Length of cable | 5 m |
| LED Function display | Yes |
| Protected against short circuits | Yes |

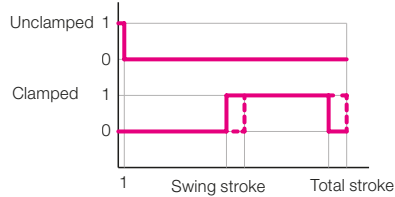
Function chart

1 = Closed
0 = Passage



Function chart

1 = On
0 = Off



Part no. for 1895- 0353-808 for 1896- 0353-809

Part no. for 1895- without switch 0353-815 for 1896- with standard switches 0353-814

Part no. O-ring (spare part)
Proximity switch 3829-077
Right angle plug 3829-088

For the evaluation of the pneumatic position monitoring we recommend a differential pressure switch, which allows a parallel connection of max. 8 swing clamps.

Further proximity switches see data sheet B 1.552

Dimensions Technical data

| | | | |
|-----------------------------------|----------------------|------------------------------------|------------------------------------|
| Max. force to pull at 250 bar | [kN] | 11.3 | 17.6 |
| Effective clamping force | [kN] | see diagram | |
| Clamping stroke | [mm] | 22 | 20 |
| Swing stroke | [mm] | 13 | 16 |
| Total stroke | [mm] | 35 ^{+0,4} _{-0,3} | 36 ^{+0,3} _{-0,2} |
| Min. operating pressure | [bar] | 30 | 30 |
| Max. flow rate | [cm ³ /s] | 20 | 36 |
| Oil volume/max. stroke | [cm ³] | 18.4 | 29.8 |
| Oil volume/max. return stroke | [cm ³] | 44.4 | 72.9 |
| a | [mm] | 27 | 37 |
| a1 only MH/MM | [mm] | 113.5 | 129 |
| a2 | [mm] | 184.5 | 200 |
| a3* only DH/DM | [mm] | 103.5 | 116 |
| b | [mm] | 43 | 55 |
| Ø b1 | [mm] | 36 | 45 |
| Ø b2 f7 | [mm] | 10 | 12 |
| c | [mm] | 31.5 | 40.5 |
| cA | [mm] | 7 | 9.5 |
| cB | [mm] | 50.5 | 72 |
| cK | [mm] | 70 | 89.5 |
| cL | [mm] | 21.5 | 25 |
| Ø d | [mm] | 32 | 40 |
| Ø d1 | [mm] | 48 | 60 |
| Ø d2 | [mm] | 54.5 | 75 |
| Ø e | [mm] | 33.5 | 45 |
| f | [mm] | 40 | 55 |
| g | [mm] | M 28x1.5 | M 35x1.5 |
| h | [mm] | 221.5 | 253.8 |
| i | [mm] | M 8 | M 10 |
| k | [mm] | 85 | 110 |
| k1 | [mm] | 27 | 35 |
| l | [mm] | 85 | 110 |
| l2 | [mm] | 27 | 35 |
| m ±1 | [mm] | 109.4 | 117.9 |
| n | [mm] | 34.5 | 47 |
| o | [mm] | 48 | 65 |
| Ø p | [mm] | 8.5 | 10.5 |
| Ø r -0.1 | [mm] | 59.8 | 79.8 |
| Ø s +1 | [mm] | 60 | 80 |
| t | [mm] | 10 | 11 |
| u | [mm] | 50.5 | 63 |
| uA | [mm] | 19 | 23 |
| uB | [mm] | 14.5 | 12.5 |
| uK | [mm] | 19 | 21 |
| uL | [mm] | 11 | 12.5 |
| v | [mm] | 61.4 | 66.4 |
| v1 | [mm] | 67 | 72 |
| v2 | [mm] | 71.9 | 76.9 |
| wA | [mm] | 11 | 13 |
| wB | [mm] | 56 | 66.5 |
| wK | [mm] | 66 | 89.5 |
| wL | [mm] | 11 | 13 |
| x ^{+0,6} _{-0,5} | [mm] | 137 | 151 |
| x max.* | [mm] | 139 | 153.6 |
| y | [mm] | 52.4 | 55.4 |
| zA | [mm] | 14 | 12 |
| zB | [mm] | 14 | 55.5 |
| zK | [mm] | 50.4 | 55.5 |
| zL | [mm] | 46 | 41 |
| SW1 | [mm] | 12 | 17 |

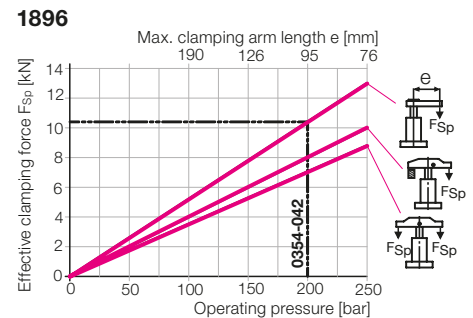
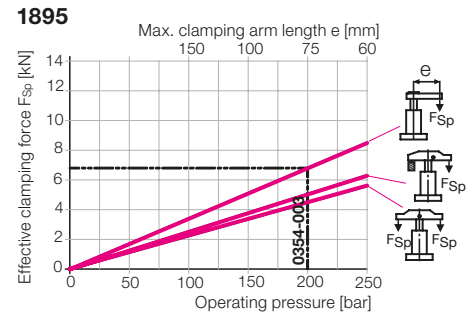
| | Part no. | Part no. |
|-------------------------------|-----------------------|-----------------------|
| Clockwise rotation 90° | 1895-304-KXX35 | 1896-304-KXX36 |
| Counterclockwise rotation 90° | 1895-404-KXX35 | 1896-404-KXX36 |
| 0 degree | 1895-444-KXX35 | 1896-444-KXX36 |

* Upper edge nut

XX: Version **DH/DM** = without/with metallic wiper without switch rod
MH/MM = without/with metallic wiper with switch rod

| Accessory | Part no. | Part no. |
|---------------------------------------|-----------------------|------------------------|
| Metallic wiper, complete (spare part) | 0341-100 | 0341-101 |
| O-ring 8x1.5 | 3000-343 | 3000-343 |
| Screw plug G 1/4 | 3610-006 | 3610-006 |
| Spare nut / tightening torque | 3527-015/90 Nm | 3527-048/160 Nm |

Effective clamping force F_{Sp} as a function of the operating pressure p



Important note!

The clamping force diagrams are only valid, if "clamping" and "locking" are controlled separately (see page 4).

Clamping arms, accessories and special clamping arms see data sheet B 1.881.

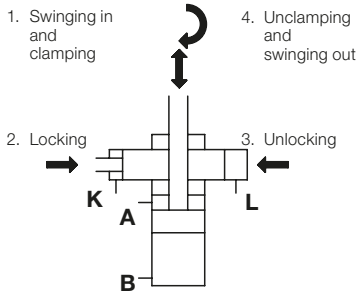
Key for available angles of rotation

| Angle of rotation ($\pm 1^\circ$) | Part no. |
|-------------------------------------|-----------------------|
| 90° | 189X-X04-KXXXX |
| 60° | 189X-X24-KXXXX |
| 45° | 189X-X34-KXXXX |

Function flow • Function chart

Hydraulic control • Important notes

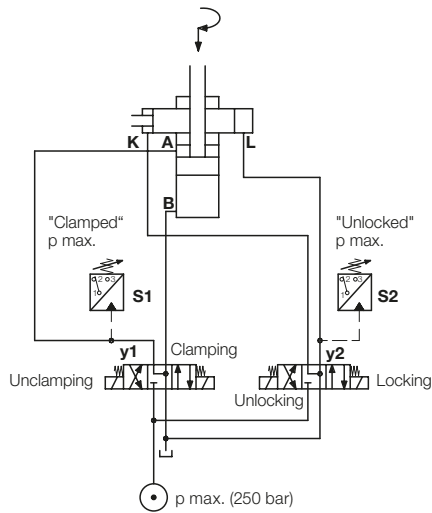
Function sequence



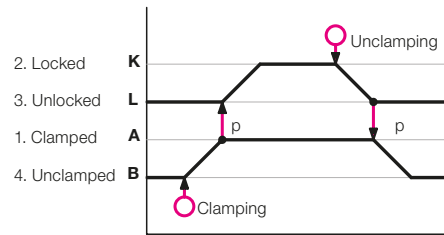
Hydraulic control

The control is effected by two separate double-acting switching circuits.

Sequence control by pressure switches



Function chart



Important notes

Swing clamps must only be used for clamping of workpieces in industrial applications and may only be operated with hydraulic oil. They can generate very high forces. The workpiece, the fixture or the machine must be in the position to compensate these forces.

In the effective area of piston rod and clamping arm there is the danger of crushing.

The manufacturer of the fixture or the machine is obliged to provide effective protection devices.

The swing clamp has no overload protection device. When mounting the clamping arm, the clamping arm or the hexagon socket in the piston have to be backed up for tightening and untightening the fixing nut.

During loading and unloading of the fixture and during clamping a collision with the clamping arm has to be avoided. Remedy: Mount position adaptor.

Operating conditions, tolerances and other data see data sheet A 0.100.

Switching sequence

1. Starting position

- y1 and y2 de-energised or
- y1 "Unclamping"; y2 "Unlocking"

2. Clamping

- 1. y1 "Clamping"; y2 de-energised
- 2. S1 = p max → y2 "Locking"

3. Depressurise (as required)

- Before depressurising, the locking pressure must be available at least for 3 seconds.
- y1 and y2 de-energised

4. Unclamping

- 1. y2 "Unlocking"
- 2. S2 = p max → y1 "Unclamping"